



National
Oceanography
Centre








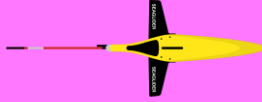





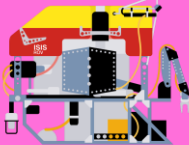






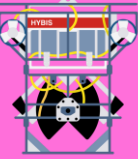
OVER THE HORIZON AND UNDER ICE ADVANCES IN MARINE ROBOTICS FROM NOC

14-06-2024

MAATEN FURLONG

NMF MARINE ROBOTICS AND AUTONOMOUS SYSTEMS (MARS) TEAMS



	Long Range Fleet		Short Range Fleet	
Operational	<div> ALR 1500 x 3</div> <div> ALR 6000 x 3</div> <div> x 6</div> <div>AUV Team</div>	<div> Slocum G2 1000 x 12</div> <div> Slocum G3 1000 x 2</div> <div> Slocum G2 200 x 10</div> <div> Slocum G3 200 x 1</div> <div> Seaglider x 9</div> <div> Waveglider x 2</div> <div> x 11</div> <div>Glider Team</div>	<div> C-Worker 4 x 2</div> <div> Autosub5</div> <div> x 6</div> <div>AUV Team</div>	<div> ISIS ROV</div> <div> Hybis</div> <div> x 7</div> <div>ROV Team</div>
Under Development	<div>Development Group</div> <div> x 25</div>		<div> Autosub Hover 1</div> <div> Sparus</div> <div> ecoSUBm</div>	<div> MPUS</div>

3 x Autosub Long Range 6000 (ALR6000)

- 2 x Pressure Vessel
- 38kWhrs Primary LTC Batteries
- 6000m depth rating
- Mass \approx 800 kg
- Length \approx 3.5m
- Top Speed \approx 1m/s
- Max Range \approx **2000km**

- 1 x Pressure vessel
- 95kWhrs Primary LTC batteries
- 1500m depth rated
- Mass \approx 800 kg
- Length \approx 3.5m
- Top Speed \approx 1m/s
- Max Range \approx **6000km**

3 x Autosub Long Range1500 (ALR1500)

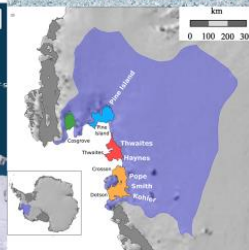
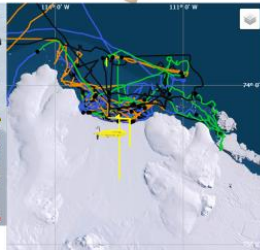
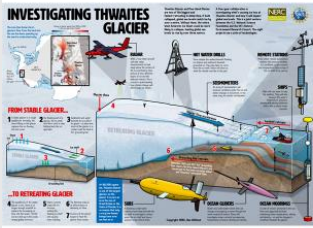


RECENT ALR MISSIONS

TARSAN – Q1 '22



Multi-day deployment of ALR1 from the Nathaniel B Palmer under Dotsen Glacier as part of TARSAN International Thwaites Glacier Collaboration
Longest track was 40km in under the ice flying at circa 100m altitude

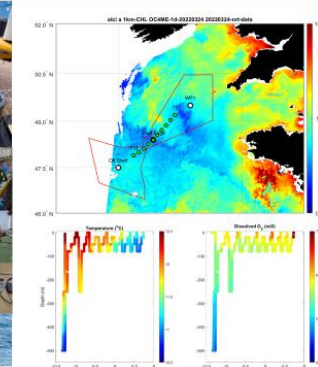


<https://thwaitesglacier.org/projects/tarsan>

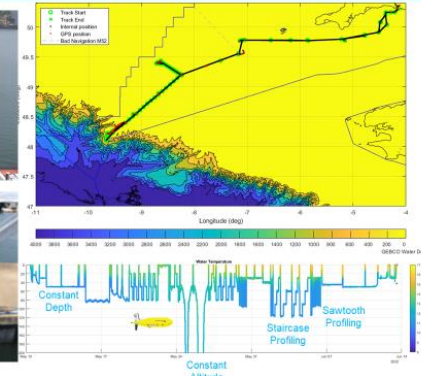
BIOGEOCHEMISTRY (DY149) – Q1 '22



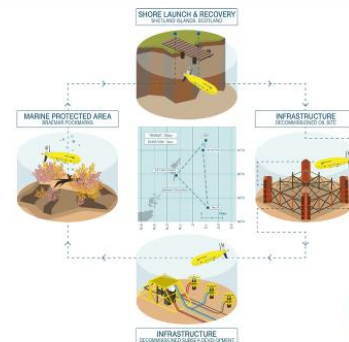
AUV	ALR2
Depth Rating	8000 m (Nominal) Currently de-rated to 800 m for sensor payload
Energy	Lithium Thionyl Chloride (~10 Days)
System sensors	<ul style="list-style-type: none"> 300 kHz RDI ADCP PNI Magnetic Heading Sensor CTD SBE 52 CTD SBE 52 MP + DO ADCPs as per system ADCPs DO SBE 43F
Science sensors	<ul style="list-style-type: none"> AutoNuts – Nutrients <ul style="list-style-type: none"> LOC Nitrate LOC Silicate LOC Iron (Chemiluminescent) LOC Iron LOC Nitrite LOC Phosphate Carcass – Carbonate <ul style="list-style-type: none"> LOC pH LOC TA LOC DIC ANB pH Stafes-App – Primary Productivity



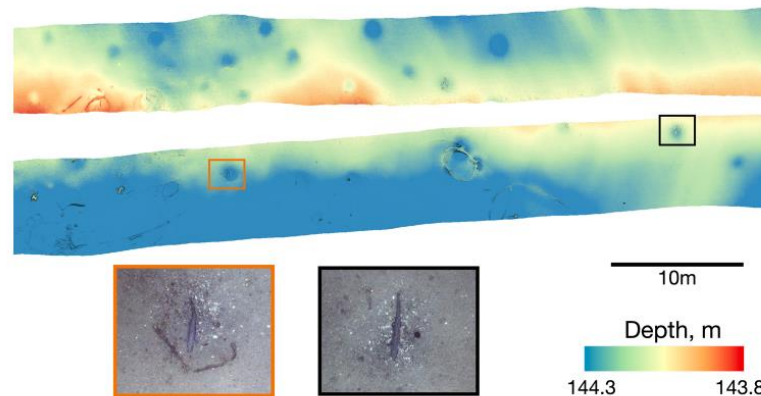
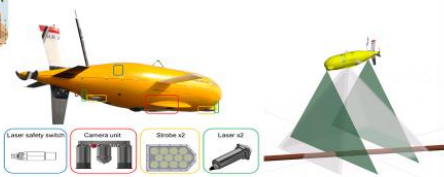
LONG DISTANCE PROVING TRIAL (LDPT) APRIL 22



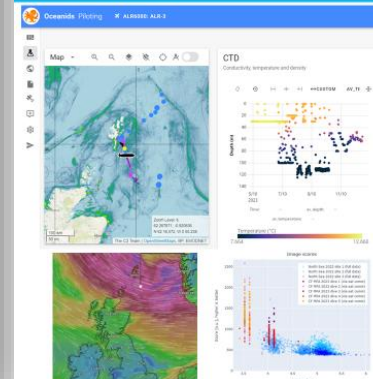
INSITE ATSEA (SEPT/OCT 2022)



- INSITE is an independent science programme examining the effects of man-made structures in the North Sea
- The Autonomous Techniques for anthropogenic Structure Ecological Assessment ATSEA project is aiming to assess the feasibility and efficacy of fully autonomous monitoring of multiple decommissioning-related sites without the aid of a support vessel by demonstrating the use of an existing shore-launched, long-range, fully autonomous underwater vehicle for marine environmental survey.



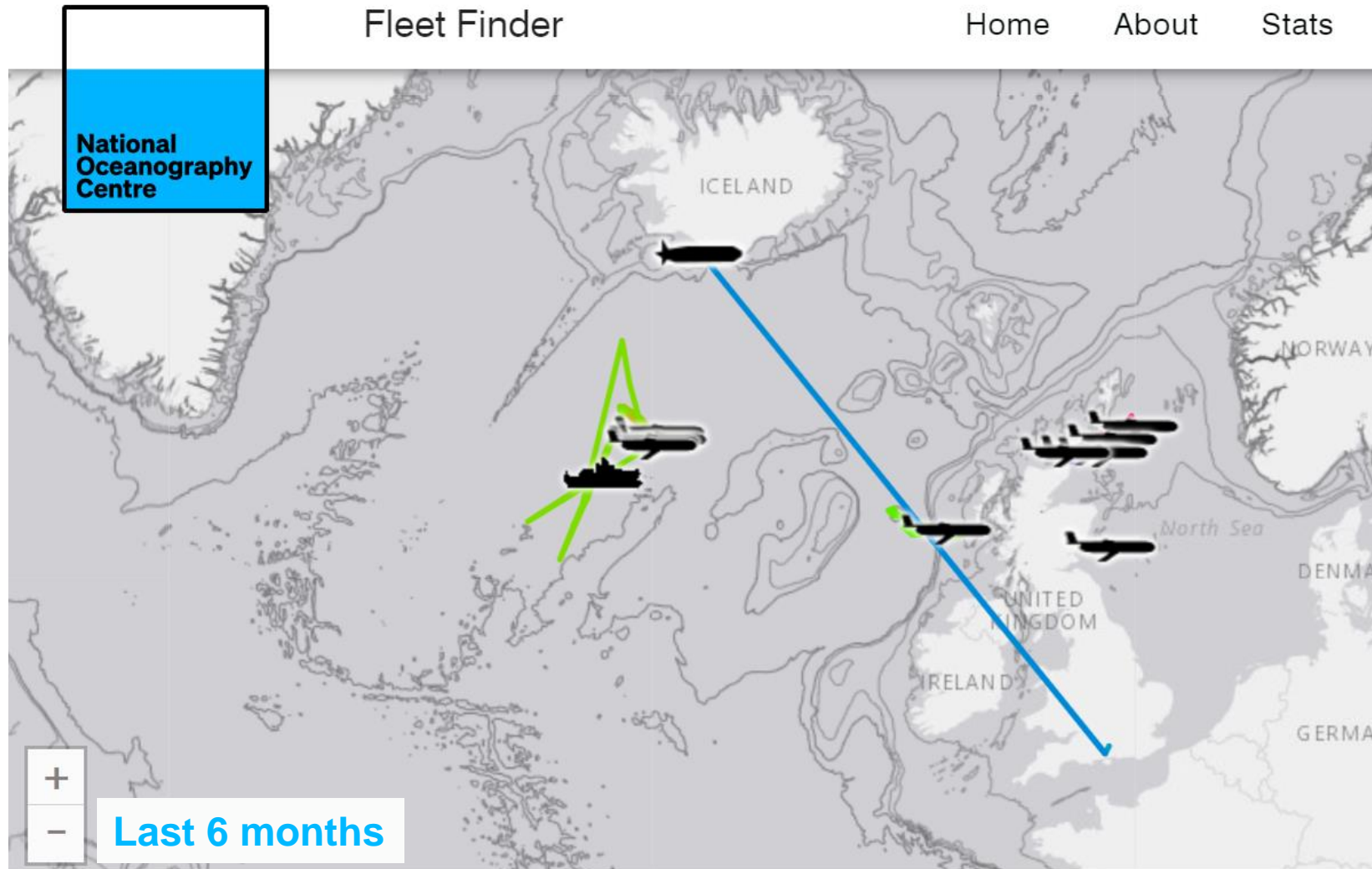
OCTOBER 2023 CENTRAL FLADDON MPA SURVEY



- ALR4 was deployed from Lerwick on the 4th October, following a short tow the AUV traversed 110 km to the Central Fladdon MPA.
- Within the MPA the system took ~1M images with the BioCAM imaging system flying between 3.5m and 4.5m altitude from the seabed.
- Having completed the survey the AUV transited back to Lerwick. Recovery was delayed by strong Autumn gales which the AUV waited out loitering subsea.



WHAT IS HAPPENING NOW (ISH)



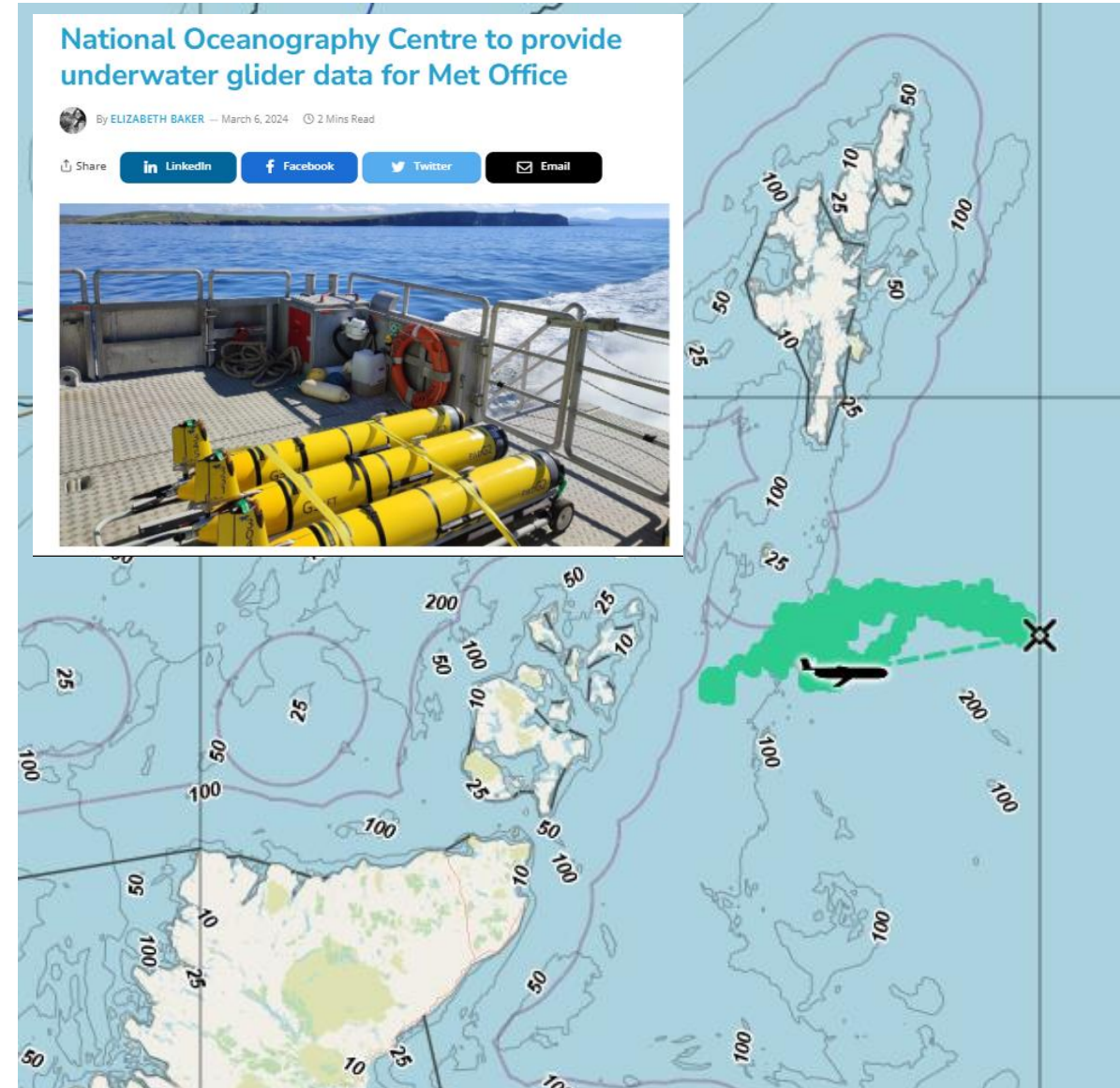
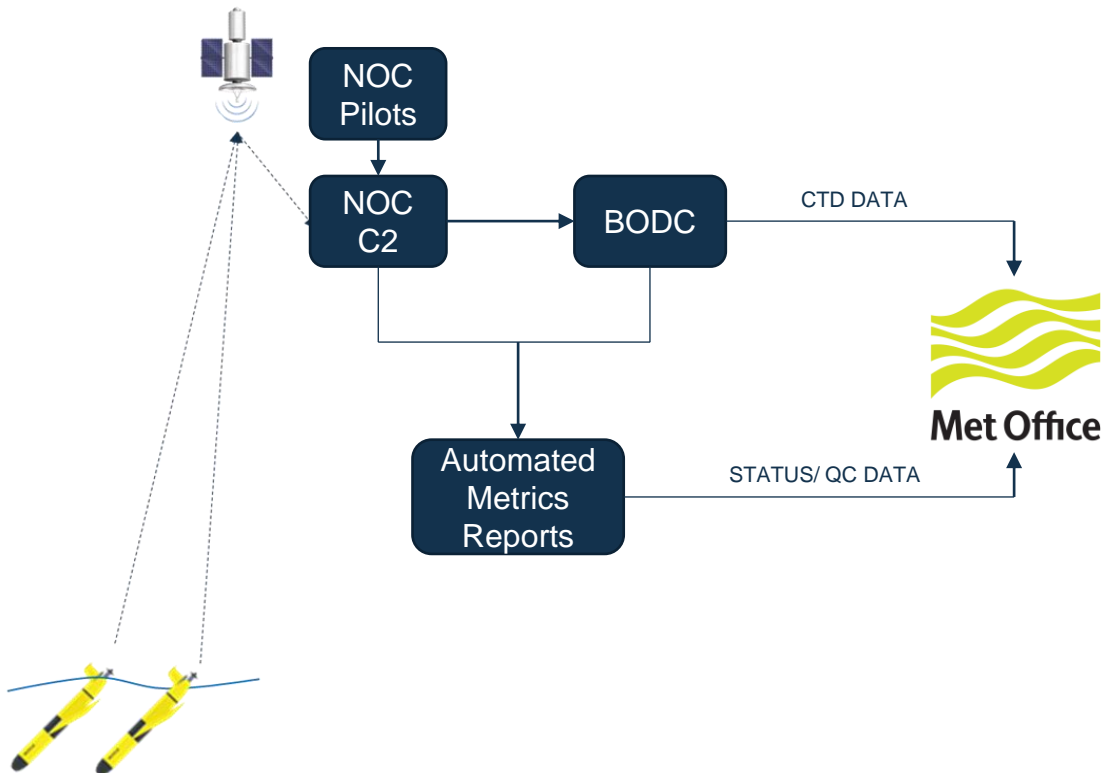
Last year of operations



MOGLI - UK MET OFFICE GLIDER PROJECT CONTINUOUS PRESENCE ON THE JONSIS LINE

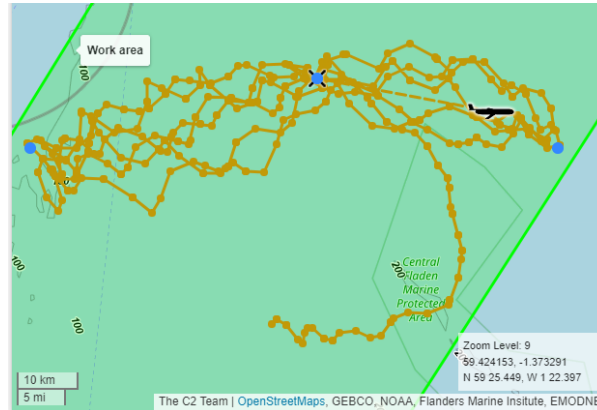
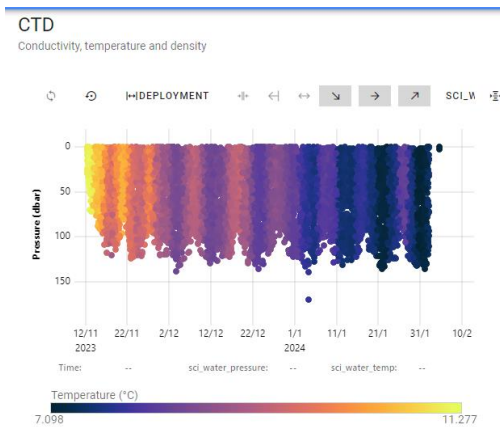


- Patrolling Western end of the JONSIS Line for last 21 months
- Providing Near Real Time Conductivity, Temperature, & Depth (CTD) Data that is fed into the AMM 15 ocean model.

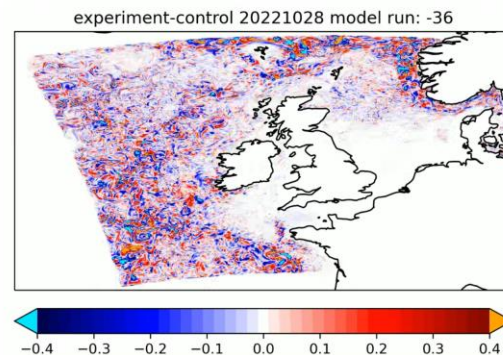


MOGLI – THE GOOD AND THE BAD

The Good – positive impact on model performance



AMM15 Results – surface temperature field difference over time



The Bad – We lost a glider



We had factored a loss into the project

BIOPOLE (DEC 23-FEB 24)



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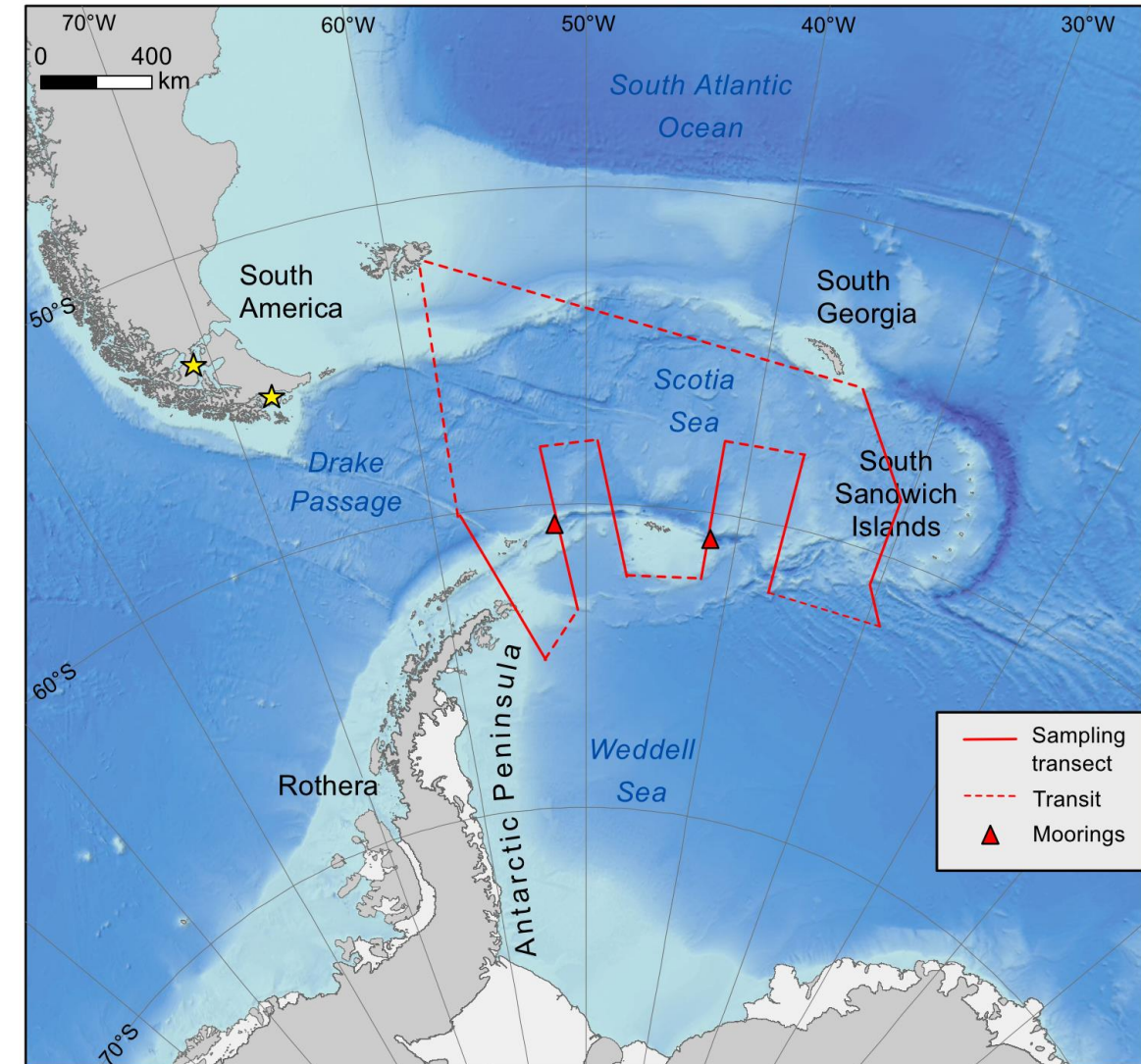


British
Antarctic Survey

NATURAL ENVIRONMENT RESEARCH COUNCIL



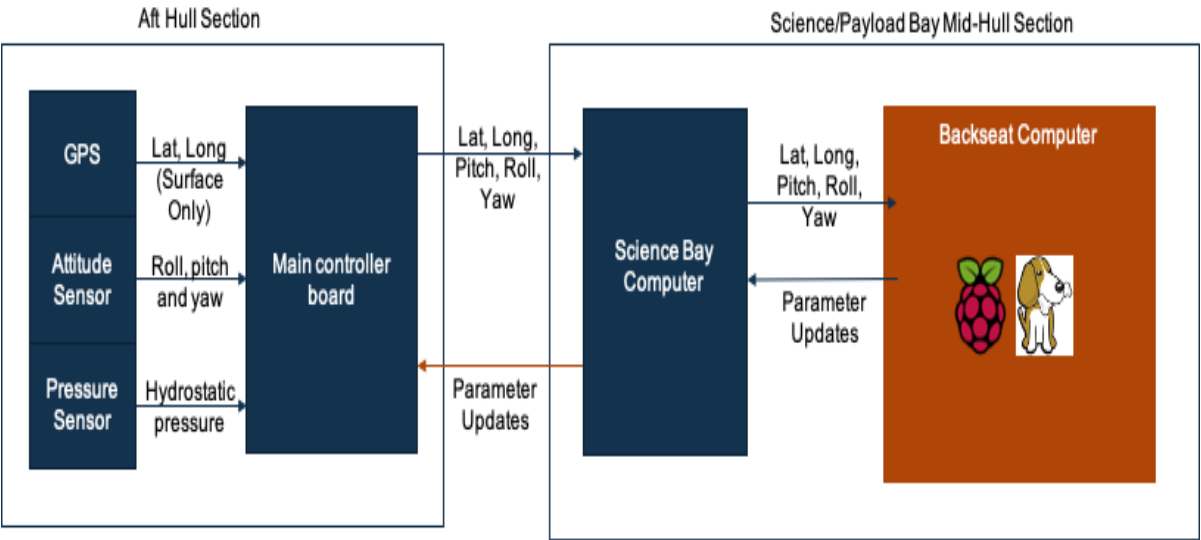
- BIOPOLE is an interdisciplinary NERC programme examining biogeochemical processes and ecosystem function in polar ecosystems.
- An Observational campaign in the Weddell sea using of ships, moorings and gliders
- Gliders made short duration missions under retreating sea ice using a Backseat Driver and upwards altimeter to enable this capability



BIPOLE – GLIDER BACK SEAT DRIVER



Goal
 Develop ice coping strategies and add to a “backseat driver” to control the gliders under ice



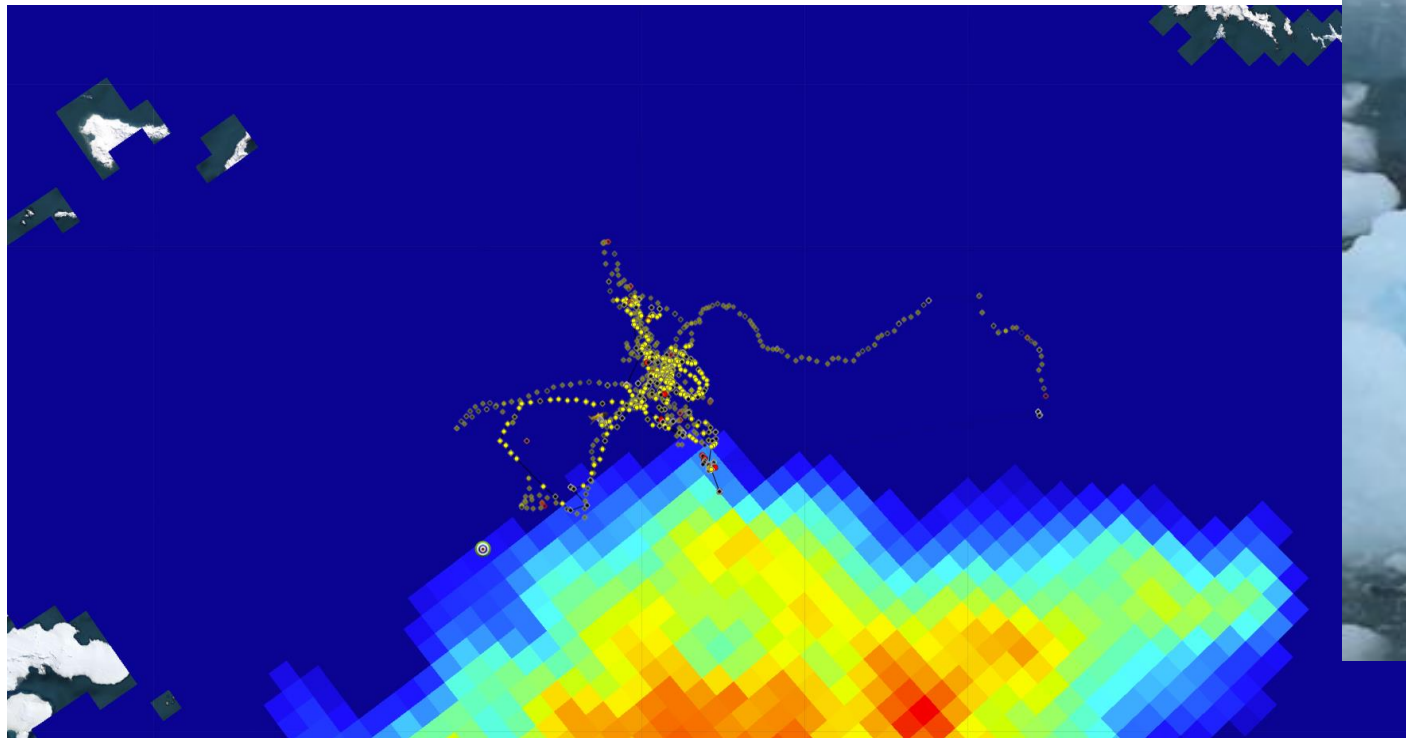
Ice sensing strategies

Median temperature	Ice draft	Ice edge
$\begin{cases} \text{Ice:} & \text{Median temp} < \text{Thresh temp} \\ \text{No ice:} & \text{Median temp} > \text{Thresh temp} \end{cases}$	<p>The ice draft D_i is</p> $D_i = D_p - D_a \cdot \cos(\theta) \in \begin{cases} (-\infty, b), & \text{uncertainty} \\ (b, +\infty), & \text{ice area} \end{cases}$ <p>D_p: CTD depth D_a: Upward-looking altitude θ: Angle of the upward-looking altimeter b: The minimum detectable ice draft</p>	<p>Boundary points location</p> $d = f(\text{mission time, ice edge})$
Figure 5. Measuring the median temperature of mixed layer.	Figure 6. Ice draft which is the difference between CTD depth and upward-looking altitude.	Figure 7. Ice edge for defining the boundary points between ice area and open water area.

Courtesy of Yaomei Wang

GLIDER OPERATIONS – IT WAS VERY DIFFICULT

Piloting using satellite data to get into and out of the marginal ice zone



Gliders just before being “munched” by the ice



Lots of lessons to learn about the environment and best approach to it

THE BIOCARBON PROGRAMME




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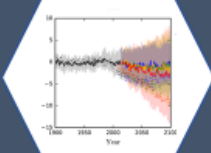
FUTURE
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RESEARCH
INFRASTRUCTURE




The major science questions



How does marine life affect the ability of seawater to absorb carbon dioxide, and how will this change?



How will the rate at which marine life consumes carbon dioxide change?



How long can marine life store carbon in the ocean and how will climate change affect this?

BIO-Carbon programme



- Focussed on understanding role of marine life in ocean carbon storage and how this will alter under climate change
- Baseline information necessary for many mCDR discussions
- Strategic Programme, £10.3M, spanning ~6 years, started 2022
- Nine projects already funded, including a gap analysis (BRICS)
- Three fieldwork projects - 6 months of activity just begun
- Final stage will be aimed at modelling and synthesis

THE BIOCARBON PROGRAMME



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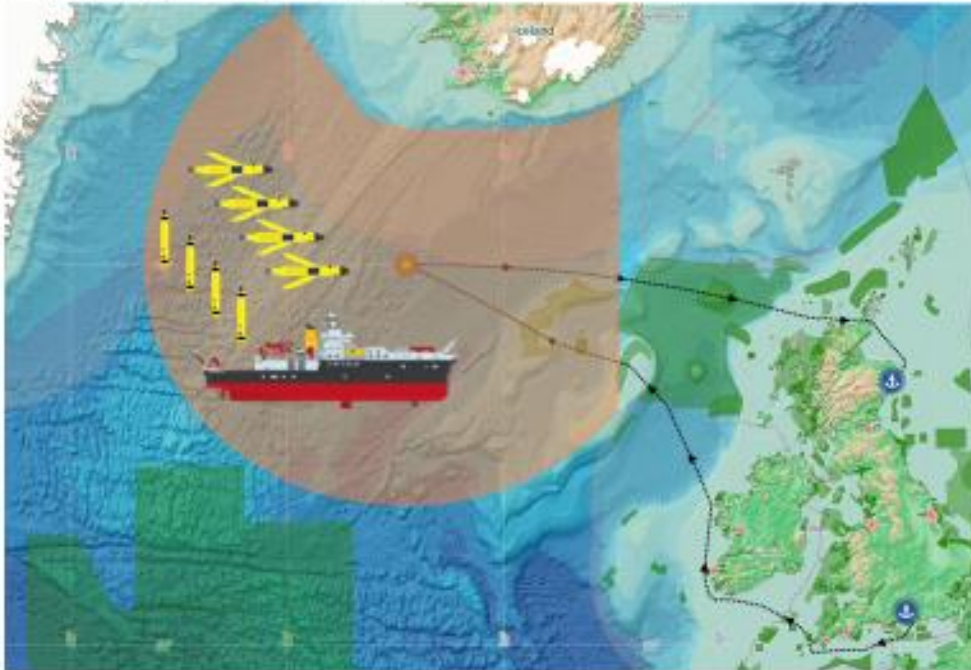


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Fieldwork

Spring cruise – DY180
21 May – 27 June



BIO-Carbon-FMRI ALR mission
June - August



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BIOCARBON ALR SPECS



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Mixed Layer ALR (ALR4)



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TRIOS RAMSES hyperspectral radiometer:
ACC-VIS (320-950nm)

LoC:

2 x OTE LoC

• TA

• DIC

4 x OTE LoC

• pH

• Nitrate

• Phosphate

• Silicate

All Via OTE Hub



eco-triplet: BBFLCD (chlorophyll, backscatter
700nm, fdom)
<https://seacatalog.com/product/wet-labs-eco-fltld-fluorometer/>

AquapHOx-LX (standalone)



UVP6: The Underwater Vision Profiler or UVP (CNRS patent) is designed to study large (>100 µm) particles and zooplankton simultaneously and to quantify them in a known volume of water. The UVP system makes use of computerised optical technology with custom lighting to acquire digital images of zooplankton IN SITU down to depths of 6000m.
http://www.hydroptic.com/index.php/public/Page/product_item/UVP6-LP



Nortek 500 DVL/ADCP: down
current measurement
<https://www.nortekgroup.com/products/dvl500-6000-m/pdf>



CTD+DO: SBE 52MP CTD and 43F
dissolved oxygen sensor.
<https://www.seabird.com/sbe-52-mp-moored-profiler-ctd-and-optional-do-sensor/product?id=60762467706>

Profiling ALR (ALR6)



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TRIOS RAMSES hyperspectral radiometer:
ACC-VIS (320-950nm)



eco-triplet: BB2FL (with chlorophyll, backscatter
532nm and 700nm)
<https://seacatalog.com/product/wet-labs-eco-fltld-fluorometer/>



MicroRider:
Turbulence Probe.
<https://rocklandscientific.com/products/modular-systems/microrider/>



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http://www.hydroptic.com/index.php/public/Page/product_item/UVP6-LP



Nortek 500 DVL/ADCP: down
current measurement
<https://www.nortekgroup.com/products/dvl500-6000-m/pdf>



CTD+DO: SBE 52MP CTD and 43F
dissolved oxygen sensor.
<https://www.seabird.com/sbe-52-mp-moored-profiler-ctd-and-optional-do-sensor/product?id=60762467706>

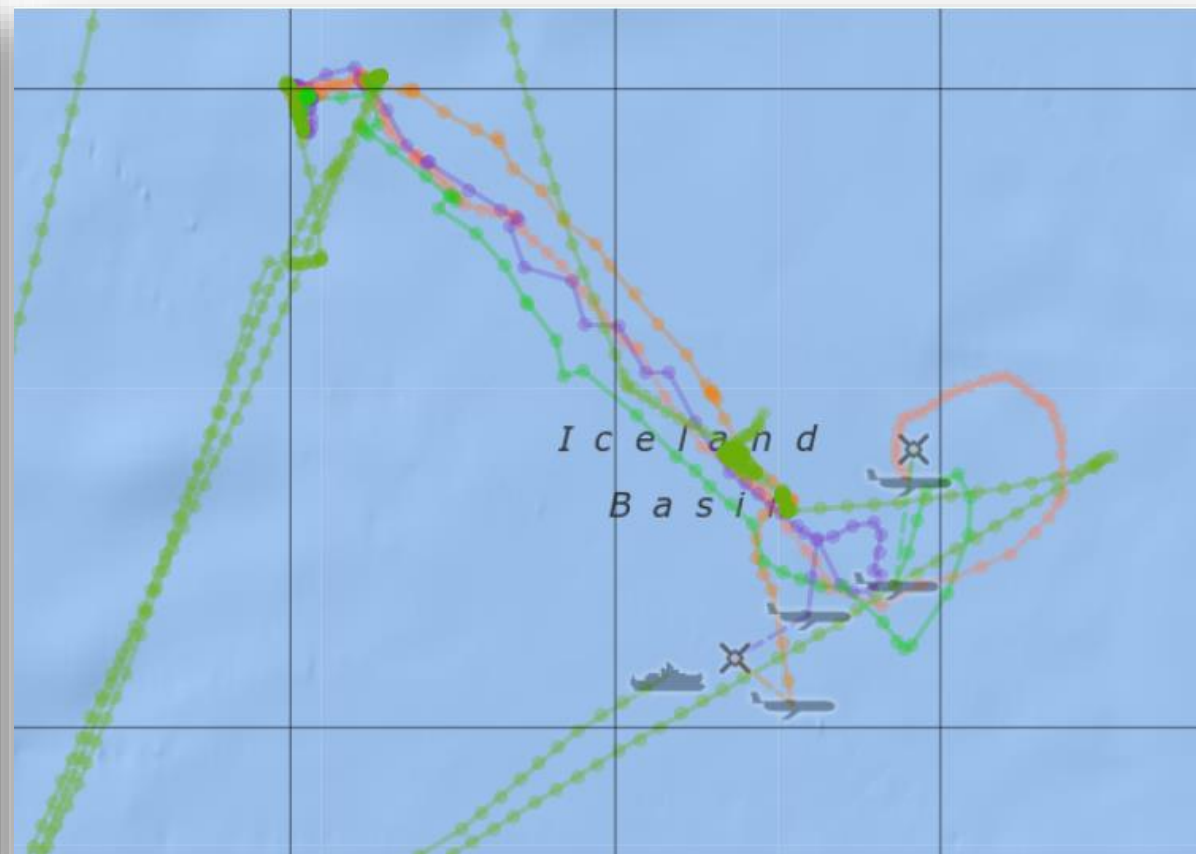
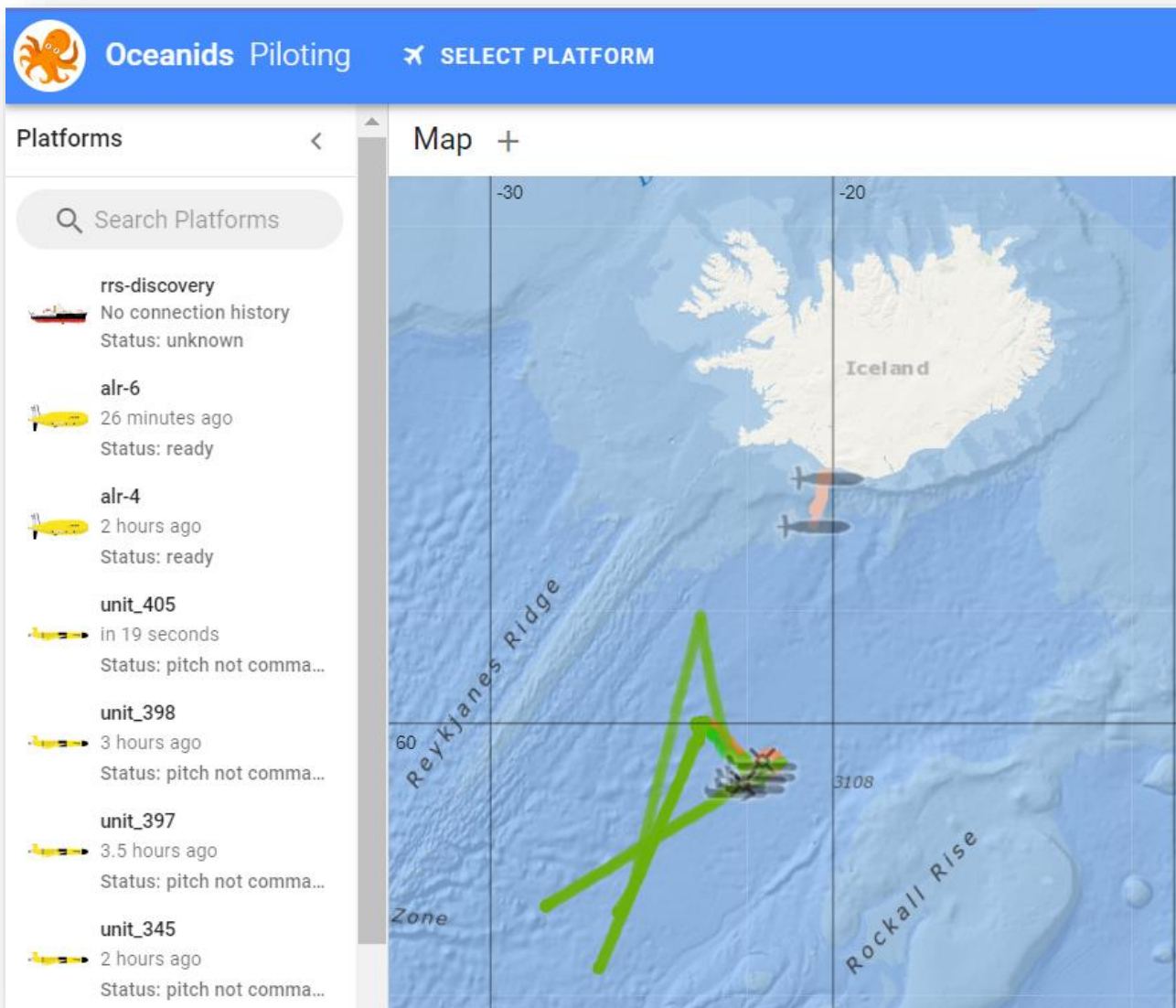
WHAT'S HAPPENING NOW?



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Follow progress on:
<https://bio-carbon.ac.uk>
<https://mars.noc.ac.uk/>

FINAL THOUGHTS – AND LESSONS LEARNED

- Marine Robotics are just other tools in the toolbox they don't replace ships but augment them
- You will lose them at some points
- To get the best out of marine robotics you need to have:
 - Staff with a deep understanding of the tech
 - Detailed knowledge of the environment you are operating in
 - Good processes and tools to support the staff
 - Luck is also always useful
- Combined ship operations and autonomy provide interesting opportunities



